Typical Class 2 System

Dynamic Positioning Control Station

Position Ref 1
Position Ref 2
Position Ref 3

Wind Sensor (2)
Gyrocompass (2)

Signal Processor Unit (SPU)

Vertical Reference Unit (2)

Bow Tunnel Thruster 1
Bow Tunnel Thruster 2
Port CP Propeller

Stem Tunnel Thruster 2
Stem Tunnel Thruster 1
Starboard CP Propeller

Port Rudder
Starboard Rudder